# Partial Order Infinitary Term Rewriting and Böhm Trees 

Patrick Bahr paba@diku.dk<br>University of Copenhagen<br>Department of Computer Science

21st International Conference on Rewriting Techniques and Applications, July 11-13, 2010

## Infinitary Term Rewriting

## Example (Infinite lists)

$$
\mathcal{R}_{\text {nats }}=\{\quad \text { from }(x) \rightarrow x: \text { from }(s(x))
$$

from(0)

## Infinitary Term Rewriting

## Example (Infinite lists)

$$
\mathcal{R}_{\text {mats }}=\{\quad \text { from }(x) \rightarrow x: \text { from }(s(x))
$$

from (0) $\rightarrow 0:$ from (1)

## Infinitary Term Rewriting

## Example (Infinite lists)

$$
\mathcal{R}_{\text {mats }}=\{\quad \text { from }(x) \rightarrow x: \text { from }(s(x))
$$

from (0) $\rightarrow^{2} 0: 1:$ from (2)

## Infinitary Term Rewriting

## Example (Infinite lists)

$$
\mathcal{R}_{\text {mats }}=\{\quad \text { from }(x) \rightarrow x: \text { from }(s(x))
$$

from (0) $\rightarrow^{3} 0: 1: 2:$ from (3)

## Infinitary Term Rewriting

## Example (Infinite lists)

$$
\mathcal{R}_{\text {mats }}=\{\quad \text { from }(x) \rightarrow x: \text { from }(s(x))
$$

from (0) $\rightarrow^{4} 0: 1: 2: 3:$ from (4)

## Infinitary Term Rewriting

## Example (Infinite lists)

$$
\mathcal{R}_{\text {mats }}=\{\quad \text { from }(x) \rightarrow x: \text { from }(s(x))
$$

from (0) $\rightarrow^{5} 0: 1: 2: 3: 4:$ from (5)

## Infinitary Term Rewriting

## Example (Infinite lists)

$$
\begin{aligned}
& \mathcal{R}_{\text {mats }}=\{\quad \text { from }(x) \rightarrow x: \text { from }(s(x)) \\
& \text { from }(0) \rightarrow^{6} 0: 1: 2: 3: 4: 5: \text { from }(6)
\end{aligned}
$$

## Infinitary Term Rewriting

## Example (Infinite lists)

$$
\mathcal{R}_{\text {mats }}=\{\quad \text { from }(x) \rightarrow x: \text { from }(s(x))
$$

from $(0) \rightarrow^{6} 0: 1: 2: 3: 4: 5:$ from $(6) \rightarrow \ldots$

## Infinitary Term Rewriting

## Example (Infinite lists)

$$
\mathcal{R}_{\text {nats }}=\{\quad \text { from }(x) \rightarrow x: \text { from }(s(x))
$$

from $(0) \rightarrow^{6} 0: 1: 2: 3: 4: 5:$ from $(6) \rightarrow \ldots$
intuitively this converges to the infinite list $0: 1: 2: 3: 4: 5$

## Infinitary Term Rewriting

## Example (Infinite lists)

$$
\mathcal{R}_{n a t s}=\{\quad \text { from }(x) \rightarrow x: \text { from }(s(x))
$$

$$
\text { from }(0) \rightarrow^{6} 0: 1: 2: 3: 4: 5: \text { from }(6) \rightarrow \ldots
$$

intuitively this converges to the infinite list $0: 1: 2: 3: 4: 5$
Infinitary term rewriting provides models that formalise the intuition above!

## Infinitary Term Rewriting

## Example (Infinite lists)

$$
\begin{aligned}
& \mathcal{R}_{\text {nats }}=\{\quad \text { from }(x) \rightarrow x: \text { from }(s(x)) \\
& \text { from }(0) \rightarrow^{6} 0: 1: 2: 3: 4: 5: \text { from }(6) \rightarrow \ldots
\end{aligned}
$$

intuitively this converges to the infinite list $0: 1: 2: 3: 4: 5$
Infinitary term rewriting provides models that formalise the intuition above!

## What is infinitary rewriting?

Term rewriting without the restriction to finite reductions.

- formalisation of the "outcome" of an infinite reduction sequence $\rightsquigarrow$ Refinement of non-termination!
- allows reduction sequences of any ordinal number length
- deals with terms of possibly infinite size


## The Metric Model of Infinitary Term Rewriting

Complete metric space $\mathcal{T}^{\infty}(\Sigma, \mathcal{V})$

- convergence is defined in terms of "usual" complete metric space on possibly infinite terms terms
- metric distance between terms is inversely proportional to the shallowest depth at which they differ:

$$
\mathbf{d}(s, t)=2^{-\operatorname{sim}(s, t)}
$$

$\operatorname{sim}(s, t)$ - depth of the shallowest discrepancy of $s$ and $t$

## The Metric Model of Infinitary Term Rewriting

Complete metric space $\mathcal{T}^{\infty}(\Sigma, \mathcal{V})$

- convergence is defined in terms of "usual" complete metric space on possibly infinite terms terms
- metric distance between terms is inversely proportional to the shallowest depth at which they differ:

$$
\mathbf{d}(s, t)=2^{-\operatorname{sim}(s, t)}
$$

$\operatorname{sim}(s, t)$ - depth of the shallowest discrepancy of $s$ and $t$
Convergence of reductions (a.k.a. strong convergence)

- convergence in the metric space, and
- rewrite rules have to (eventually) be applied at increasingly large depth


## The Metric Model of Infinitary Term Rewriting

Complete metric space $\mathcal{T}^{\infty}(\Sigma, \mathcal{V})$

- convergence is defined in terms of "usual" complete metric space on possibly infinite terms terms
- metric distance between terms is inversely proportional to the shallowest depth at which they differ:

$$
\mathbf{d}(s, t)=2^{-\operatorname{sim}(s, t)}
$$

$\operatorname{sim}(s, t)$ - depth of the shallowest discrepancy of $s$ and $t$
Convergence of reductions (a.k.a. strong convergence)

- convergence in the metric space, and
- rewrite rules have to (eventually) be applied at increasingly large depth $\rightsquigarrow$ convergence of a reduction: depth at which the rewrite rules are applied tends to infinity


## Example: Convergence of a Reduction

$$
\mathcal{R}=\{a \rightarrow g(a)\}
$$

## Example: Convergence of a Reduction

$$
\mathcal{R}=\{a \rightarrow g(a)\}
$$

## Example: Convergence of a Reduction


$\mathcal{R}=\{a \rightarrow g(a)\}$

## Example: Convergence of a Reduction


$\mathcal{R}=\{a \rightarrow g(a)\}$

## Example: Convergence of a Reduction


$\mathcal{R}=\{a \rightarrow g(a)\}$

## Example: Convergence of a Reduction


$\mathcal{R}=\{a \rightarrow g(a)\}$

## Example: Convergence of a Reduction


$\mathcal{R}=\{a \rightarrow g(a)\}$

Example: Convergence of a Reduction


Example: Convergence of a Reduction

$$
\mathcal{R}=\{a \rightarrow g(a)\}
$$

## Example: Convergence of a Reduction


$f(a) \rightarrow \underset{\mathcal{R}}{\omega} f\left(g^{\omega}\right)$

## Example: Non-Convergence of a Reduction



$$
\mathcal{R}=\left\{\begin{array}{c}
a \rightarrow g(a) \\
h(x) \rightarrow h(g(x))
\end{array}\right.
$$

## Example: Non-Convergence of a Reduction



$$
\mathcal{R}=\left\{\begin{array}{c}
a \rightarrow g(a) \\
h(x) \rightarrow h(g(x))
\end{array}\right.
$$

## Example: Non-Convergence of a Reduction



$$
\mathcal{R}=\left\{\begin{aligned}
a & \rightarrow g(a) \\
h(x) & \rightarrow h(g(x))
\end{aligned}\right.
$$

## Example: Non-Convergence of a Reduction



$$
\mathcal{R}=\left\{\begin{array}{c}
a \rightarrow g(a) \\
h(x) \rightarrow h(g(x))
\end{array}\right.
$$

## Example: Non-Convergence of a Reduction



$$
\mathcal{R}=\left\{\begin{array}{c}
a \rightarrow g(a) \\
h(x) \rightarrow h(g(x))
\end{array}\right.
$$

## Example: Non-Convergence of a Reduction



$$
\mathcal{R}=\left\{\begin{aligned}
a & \rightarrow g(a) \\
h(x) & \rightarrow h(g(x))
\end{aligned}\right.
$$

## Example: Non-Convergence of a Reduction



$$
\mathcal{R}=\left\{\begin{aligned}
a & \rightarrow g(a) \\
h(x) & \rightarrow h(g(x))
\end{aligned}\right.
$$

## Example: Non-Convergence of a Reduction



$$
\mathcal{R}=\left\{\begin{aligned}
a & \rightarrow g(a) \\
h(x) & \rightarrow h(g(x))
\end{aligned}\right.
$$

## Example: Non-Convergence of a Reduction



$$
\mathcal{R}=\left\{\begin{aligned}
a & \rightarrow g(a) \\
h(x) & \rightarrow h(g(x))
\end{aligned}\right.
$$

## Example: Non-Convergence of a Reduction



$$
\mathcal{R}=\left\{\begin{aligned}
a & \rightarrow g(a) \\
h(x) & \rightarrow h(g(x))
\end{aligned}\right.
$$

## Example: Non-Convergence of a Reduction



$$
\mathcal{R}=\left\{\begin{aligned}
a & \rightarrow g(a) \\
h(x) & \rightarrow h(g(x))
\end{aligned}\right.
$$

## Example: Non-Convergence of a Reduction



$$
\mathcal{R}=\left\{\begin{aligned}
a & \rightarrow g(a) \\
h(x) & \rightarrow h(g(x))
\end{aligned}\right.
$$

## Issues of the Metric Model

- Notion of convergence is too restrictive!
(no notion of local convergence)
- Orthogonal TRSs are not infinitary confluent!


## Issues of the Metric Model

- Notion of convergence is too restrictive!
(no notion of local convergence)
- Orthogonal TRSs are not infinitary confluent!


## Infinitary confluence



For every $t, t_{1}, t_{2} \in \mathcal{T}^{\infty}(\Sigma, \mathcal{V})$ with $t_{1} \leftrightarrow t \rightarrow t_{2}$

## Issues of the Metric Model

- Notion of convergence is too restrictive!
(no notion of local convergence)
- Orthogonal TRSs are not infinitary confluent!

Infinitary confluence


For every $t, t_{1}, t_{2} \in \mathcal{T}^{\infty}(\Sigma, \mathcal{V})$ with $t_{1} \leftrightarrow t \rightarrow t_{2}$ there is a $t^{\prime} \in \mathcal{T}^{\infty}(\Sigma, \mathcal{V})$ with $t_{1} \rightarrow t^{\prime} \leftrightarrow t_{2}$

## Infinitary Confluence

$$
\mathcal{R}=\{f(x) \rightarrow x \quad g(x) \rightarrow x\}
$$



## Infinitary Confluence

$$
\mathcal{R}=\{f(x) \rightarrow x \quad g(x) \rightarrow x\}
$$



## Infinitary Confluence

$$
\mathcal{R}=\{f(x) \rightarrow x \quad g(x) \rightarrow x\}
$$



## Infinitary Confluence

$$
\mathcal{R}=\{f(x) \rightarrow x \quad g(x) \rightarrow x\}
$$



## Infinitary Confluence

$$
\mathcal{R}=\{f(x) \rightarrow x \quad g(x) \rightarrow x\}
$$



## Infinitary Confluence

$$
\mathcal{R}=\{f(x) \rightarrow x \quad g(x) \rightarrow x\}
$$



## Infinitary Confluence

$$
\mathcal{R}=\{f(x) \rightarrow x \quad g(x) \rightarrow x\}
$$



## Infinitary Confluence

$$
\mathcal{R}=\{f(x) \rightarrow x \quad g(x) \rightarrow x\}
$$



Infinitary Confluence

$$
\mathcal{R}=\{f(x) \rightarrow x \quad g(x) \rightarrow x\}
$$



## Meaningless Terms [Kennaway et al. 1999]

Infinitary confluence can be obtained by rewriting modulo meaningless terms:

Definition (root-active terms)
A term $t$ is root-active if for each $t \rightarrow^{*} t^{\prime}$ there is a $t^{\prime} \rightarrow^{*} s$ with $s$ a redex.

## Meaningless Terms [Kennaway et al. 1999]

Infinitary confluence can be obtained by rewriting modulo meaningless terms:

## Definition (root-active terms)

A term $t$ is root-active if for each $t \rightarrow^{*} t^{\prime}$ there is a $t^{\prime} \rightarrow^{*} s$ with $s$ a redex.

## Definition (Böhm extension)

The Böhm extension $\mathcal{B}$ of a TRS $\mathcal{R}$ extends $\mathcal{R}$ by a fresh symbol $\perp$ and additional rules $t \rightarrow \perp$, where $t \neq \perp$ is a root-active term with some of its root-active subterms substituted by $\perp$.

## Meaningless Terms [Kennaway et al. 1999]

Infinitary confluence can be obtained by rewriting modulo meaningless terms:

## Definition (root-active terms)

A term $t$ is root-active if for each $t \rightarrow^{*} t^{\prime}$ there is a $t^{\prime} \rightarrow^{*} s$ with $s$ a redex.

## Definition (Böhm extension)

The Böhm extension $\mathcal{B}$ of a TRS $\mathcal{R}$ extends $\mathcal{R}$ by a fresh symbol $\perp$ and additional rules $t \rightarrow \perp$, where $t \neq \perp$ is a root-active term with some of its root-active subterms substituted by $\perp$.

## Theorem ([Kennaway et al. 1999])

The Böhm extension $\mathcal{B}$ of an orthogonal TRS is both infinitarily confluent and infinitarily normalising.

## Meaningless Terms [Kennaway et al. 1999]

Infinitary confluence can be obtained by rewriting modulo meaningless terms:

## Definition (root-active terms)

A term $t$ is root-active if for each $t \rightarrow^{*} t^{\prime}$ there is a $t^{\prime} \rightarrow^{*} s$ with $s$ a redex.

## Definition (Böhm extension)

The Böhm extension $\mathcal{B}$ of a TRS $\mathcal{R}$ extends $\mathcal{R}$ by a fresh symbol $\perp$ and additional rules $t \rightarrow \perp$, where $t \neq \perp$ is a root-active term with some of its root-active subterms substituted by $\perp$.

## Theorem ([Kennaway et al. 1999])

The Böhm extension $\mathcal{B}$ of an orthogonal TRS is both infinitarily confluent and infinitarily normalising.
The unique normal form of a term w.r.t. $\mathcal{B}$ is called its Böhm tree.

## Meaningless Terms [Kennaway et al. 1999]

Infinitary confluence can be obtained by rewriting modulo meaningless terms:

## Definition (root-active terms)

A term $t$ is root-active if for each $t \rightarrow^{*} t^{\prime}$ there is a $t^{\prime} \rightarrow^{*} s$ with $s$ a redex.

## Definition (Böhm extension)

The Böhm extension $\mathcal{B}$ of a TRS $\mathcal{R}$ extends $\mathcal{R}$ by a fresh symbol $\perp$ and additional rules $t \rightarrow \perp$, where $t \neq \perp$ is a root-active term with some of its root-active subterms substituted by $\perp$.

## Example (infinitary confluence)

$$
f(g(f(g(\ldots)))) \longrightarrow g^{\omega}
$$

$$
\mathcal{R}=\left\{\begin{array}{l}
f(x) \rightarrow x \\
g(x) \rightarrow x
\end{array}\right.
$$

## Meaningless Terms [Kennaway et al. 1999]

Infinitary confluence can be obtained by rewriting modulo meaningless terms:

## Definition (root-active terms)

A term $t$ is root-active if for each $t \rightarrow^{*} t^{\prime}$ there is a $t^{\prime} \rightarrow^{*} s$ with $s$ a redex.

## Definition (Böhm extension)

The Böhm extension $\mathcal{B}$ of a $\operatorname{TRS} \mathcal{R}$ extends $\mathcal{R}$ by a fresh symbol $\perp$ and additional rules $t \rightarrow \perp$, where $t \neq \perp$ is a root-active term with some of its root-active subterms substituted by $\perp$.

## Example (infinitary confluence)



$$
\mathcal{R}=\left\{\begin{array}{l}
f(x) \rightarrow x \\
g(x) \rightarrow x
\end{array}\right.
$$

## Outline

## (1) Introduction

- Infinitary Term Rewriting
- The Metric Model
- Issues of the Metric Model
- Meaningless Terms and Böhm Trees
(2) The Partial Order Model
- Formal Definition
- Properties of the Partial Order Model
- And Böhm Trees?
(3) Conclusion


## Partial Order Model of Infinitary Term Rewriting

## Partial order on terms

- partial terms: terms with additional constant $\perp$ (read as "undefined")
- partial order $\leq_{\perp}$ reads as: "is less defined than"
- $\leq_{\perp}$ is a complete semilattice ( $=$ cpo + glbs of non-empty sets)


## Partial Order Model of Infinitary Term Rewriting

## Partial order on terms

- partial terms: terms with additional constant $\perp$ (read as "undefined")
- partial order $\leq_{\perp}$ reads as: "is less defined than"
- $\leq_{\perp}$ is a complete semilattice ( $=$ cpo + glbs of non-empty sets)


## Convergence

- formalised by the limit inferior:

$$
\liminf _{\iota \rightarrow \alpha} t_{\iota}=\bigsqcup_{\beta<\alpha} \prod_{\beta \leq \iota<\alpha} t_{\iota}
$$

## Partial Order Model of Infinitary Term Rewriting

## Partial order on terms

- partial terms: terms with additional constant $\perp$ (read as "undefined")
- partial order $\leq_{\perp}$ reads as: "is less defined than"
- $\leq_{\perp}$ is a complete semilattice ( $=$ cpo + glbs of non-empty sets)


## Convergence

- formalised by the limit inferior:

$$
\liminf _{\iota \rightarrow \alpha} t_{\iota}=\bigsqcup_{\beta<\alpha} \prod_{\beta \leq \iota<\alpha} t_{\iota}
$$

- intuition: eventual persistence of nodes of the terms
- convergence: limit inferior of the contexts of the reduction

An Example


An Example


An Example


## Properties of the Partial Order Model

## Benefits

- reduction sequences always converge
- more fine-grained than the metric model
- more intuitive than the metric model
- subsumes metric model, i.e. both models agree on total reductions


## Properties of the Partial Order Model

## Benefits

- reduction sequences always converge
- more fine-grained than the metric model
- more intuitive than the metric model
- subsumes metric model, i.e. both models agree on total reductions


## Definition (total reduction)

A reduction is called total if all its terms are total.

## Properties of the Partial Order Model

## Benefits

- reduction sequences always converge
- more fine-grained than the metric model
- more intuitive than the metric model
- subsumes metric model, i.e. both models agree on total reductions


## Definition (total reduction)

A reduction is called total if all its terms are total.
Theorem (total $p$-convergence $=m$-convergence)
(1) For every reduction $S$ in a $T R S, S: s \xrightarrow{p} t$ is total iff $S: s \xrightarrow{m} t$.

## Properties of the Partial Order Model

## Benefits

- reduction sequences always converge
- more fine-grained than the metric model
- more intuitive than the metric model
- subsumes metric model, i.e. both models agree on total reductions


## Definition (total reduction)

A reduction is called total if all its terms are total.

## Theorem (total $p$-convergence $=m$-convergence)

(1) For every reduction $S$ in a TRS, $S: s_{\xrightarrow{p}} t$ is total iff $S: s \xrightarrow{m} t$.
(2) For orthogonal TRS, s $\xrightarrow[\rightarrow]{p_{\rightarrow}} t$ iff $s \xrightarrow{m} t$, provided $s, t$ are total.

## Partial Order Model vs. Metric Model

## Properties of orthogonal systems

| property | metric | partial order |
| :--- | :--- | :--- |
| compression |  |  |
| finite approximation |  |  |
| complete developments |  |  |
| infinitary confluence |  |  |
| infinitary normalisation |  |  |
|  |  |  |

## Partial Order Model vs. Metric Model

Properties of orthogonal systems

| property | metric partial order |  |
| :--- | :--- | :--- |
| compression |  |  |
| finite approximation |  |  |
| complete developments |  |  |
| infinitary confluence |  |  |
| infinitary normalisation |  |  |

Compression
Every reduction can be performed in at most $\omega$ steps:

$$
s \rightarrow^{\alpha} t \quad \Longrightarrow \quad s \rightarrow \leq \omega t
$$

## Partial Order Model vs. Metric Model

Properties of orthogonal systems

| property | metric partial order |  |
| :--- | :---: | :---: |
| compression |  |  |
| finite approximation |  |  |
| complete developments |  |  |
| infinitary confluence |  |  |
| infinitary normalisation |  |  |

Compression
Every reduction can be performed in at most $\omega$ steps:

$$
s \rightarrow^{\alpha} t \quad \Longrightarrow \quad s \rightarrow \leq \omega t
$$

## Partial Order Model vs. Metric Model

## Properties of orthogonal systems

| property | metric | partial order |
| :--- | :---: | :---: |
| compression |  |  |
| finite approximation |  |  |
| complete developments |  |  |
| infinitary confluence |  |  |
| infinitary normalisation |  |  |
|  |  |  |

## Finite approximation

Every outcome can be approximated by a finite reduction arbitrary well:

$$
s \rightarrow^{\alpha} t \quad \Longrightarrow \quad \forall d \in \mathbb{N} \exists t^{\prime}\left\{\begin{array}{l}
s \rightarrow^{*} t^{\prime} \\
t \text { and } t^{\prime} \text { coincide up to depth } d
\end{array}\right.
$$

## Partial Order Model vs. Metric Model

## Properties of orthogonal systems

| property | metric | partial order |
| :--- | :---: | :---: |
| compression |  |  |
| finite approximation |  |  |
| complete developments |  |  |
| infinitary confluence |  |  |
| infinitary normalisation |  |  |

## Finite approximation

Every outcome can be approximated by a finite reduction arbitrary well:

$$
s \rightarrow^{\alpha} t \quad \Longrightarrow \quad \forall d \in \mathbb{N} \exists t^{\prime}\left\{\begin{array}{l}
s \rightarrow^{*} t^{\prime} \\
t \text { and } t^{\prime} \text { coincide up to depth } d
\end{array}\right.
$$

## Partial Order Model vs. Metric Model

## Properties of orthogonal systems

| property | metric | partial order |
| :--- | :---: | :---: |
| compression |  |  |
| finite approximation |  |  |
| complete developments |  |  |
| infinitary confluence |  |  |
| infinitary normalisation |  |  |

## Complete developments

 reductions simulating simultaneous contraction of a set of redexes
## Partial Order Model vs. Metric Model

Properties of orthogonal systems

| property | metric | partial order |
| :--- | :---: | :---: |
| compression | $\checkmark$ | $\checkmark$ |
| finite approximation | $\checkmark$ | $\checkmark$ |
| complete developments | $\times$ | $\checkmark$ |
| infinitary confluence |  |  |
| infinitary normalisation |  |  |

Complete developments reductions simulating simultaneous contraction of a set of redexes

## Partial Order Model vs. Metric Model

## Properties of orthogonal systems

| property | metric | partial order |
| :--- | :---: | :---: |
| compression | $\checkmark$ | $\checkmark$ |
| finite approximation | $\checkmark$ | $\checkmark$ |
| complete developments | $x$ | $\checkmark$ |
| infinitary confluence |  |  |
| infinitary normalisation |  |  |

Infinitary confluence


## Partial Order Model vs. Metric Model

## Properties of orthogonal systems

| property | metric | partial order |
| :--- | :---: | :---: |
| compression | $\checkmark$ |  |
| finite approximation | $\checkmark$ |  |
| complete developments | $x$ |  |
| infinitary confluence | $x$ |  |
| infinitary normalisation |  |  |

Infinitary confluence


## Partial Order Model vs. Metric Model

Properties of orthogonal systems

| property | metric | partial order |
| :--- | :---: | :---: |
| compression | $\checkmark$ | $\checkmark$ |
| finite approximation | $\checkmark$ | $\checkmark$ |
| complete developments | $x$ | $\checkmark$ |
| infinitary confluence | $x$ | $\checkmark$ |
| infinitary normalisation |  |  |

## Infinitary normalisation

every term has a normal form reachable by a possibly infinite reduction

## Partial Order Model vs. Metric Model

Properties of orthogonal systems

| property | metric | partial order |
| :--- | :---: | :---: |
| compression | $\checkmark$ | $\checkmark$ |
| finite approximation | $\checkmark$ | $\checkmark$ |
| complete developments | $x$ | $\checkmark$ |
| infinitary confluence | $x$ | $\checkmark$ |
| infinitary normalisation | $X$ | $\checkmark$ |

## Infinitary normalisation

every term has a normal form reachable by a possibly infinite reduction

## Partial Order Model vs. Metric Model

## Properties of orthogonal systems

| property | metric | partial order |
| :--- | :---: | :---: |
| compression |  |  |
| finite approximation | $\boxed{x}$ |  |
| complete developments | $X$ |  |
| infinitary confluence | $X$ |  |
| infinitary normalisation | $X$ |  |

## Unique normal forms

In an orthogonal TRS, every term has a unique normal form w.r.t. $p$-convergence.

## And Böhm Trees?

Recall: total $p$-reachability $=m$-reachability
If $\mathcal{R}$ is an orthogonal TRS and $s, t$ total terms, then

$$
s \stackrel{p}{\rightarrow}_{\mathcal{R}} t \quad \text { iff } \quad s \xrightarrow{m}_{\mathcal{R}} t .
$$

## And Böhm Trees?

Recall: total $p$-reachability $=m$-reachability
If $\mathcal{R}$ is an orthogonal TRS and $s, t$ total terms, then

$$
s{\xrightarrow{p_{\rightarrow}} \mathcal{R}} t \quad \text { iff } \quad s \xrightarrow{m}_{\mathcal{R}} t .
$$

Theorem ( $p$-reachability = Böhm-reachability)
If $\mathcal{R}$ is an orthogonal TRS and $\mathcal{B}$ the Böhm extension of $\mathcal{R}$, then

$$
s \xrightarrow{p}_{\mathcal{R}} t \quad \text { iff } \quad s \xrightarrow{m}_{\mathcal{B}} t .
$$

## And Böhm Trees?

Recall: total $p$-reachability $=m$-reachability
If $\mathcal{R}$ is an orthogonal TRS and $s, t$ total terms, then

$$
s \xrightarrow{p_{\rightarrow}} \mathcal{R} t \quad \text { iff } \quad s \xrightarrow{m}_{\mathcal{R}} t
$$

Theorem (p-reachability = Böhm-reachability)
If $\mathcal{R}$ is an orthogonal TRS and $\mathcal{B}$ the Böhm extension of $\mathcal{R}$, then

$$
s \xrightarrow{p}_{\mathcal{R}} t \quad \text { iff } \quad s \xrightarrow{m}_{\mathcal{B}} t .
$$

## Böhm Trees

The unique normal form of a term in an orthogonal TRS w.r.t. $p$-convergence is its Böhm Tree (w.r.t. root-active terms).

## What have we gained?

## Benefits over the metric model

- local notion of convergence (eventual persistence of nodes)
$\rightsquigarrow$ more intuitive than the metric model
- reduction sequences always converge
- more fine-grained than the metric model
- subsumes metric model, i.e. both models agree on total reductions
- orthogonal systems are infinitarily confluent and normalising


## What have we gained?

## Benefits over the metric model

- local notion of convergence (eventual persistence of nodes) $\rightsquigarrow$ more intuitive than the metric model
- reduction sequences always converge
- more fine-grained than the metric model
- subsumes metric model, i.e. both models agree on total reductions
- orthogonal systems are infinitarily confluent and normalising

Benefits over Böhm extensions

- it is simpler and more natural
- Böhm extensions contain in general infinitely many rules with infinite left-hand sides
- provides intrinsic characterisation of root-active terms


## References

國 Salvador Lucas．
Transfinite Rewriting Semantics for Term Rewriting Systems．
Rewriting Techniques and Applications，RTA， 2001.
國 Stefan Blom
Term Graph Rewriting－Syntax and Semantics．
PhD Thesis，Vrije Universiteit te Amsterdam， 2001.
Kennaway，Klop，Sleep and de Vries．
On the adequacy of graph rewriting for simulating term rewriting． ACM TOPLAS， 1994.

國 Paola Inverardi and Monica Nesi．
Deciding observational congruence of finite－state CCS expressions by rewriting．
Theoretical Computer Science， 1995.

## References (contd.)

围 Richard Kennaway, Vincent van Oostrom, and Fer-Jan de Vries.
Meaningless terms in rewriting.
Journal of Functional and Logic Programming, 1999(1):1-35, February 1999.

國 Jeroen Ketema.
Böhm-Like Trees for Rewriting.
PhD thesis, Vrije Universiteit Amsterdam, 2006.
Stefan Blom.
An approximation based approach to infinitary lambda calculi. Rewriting Techniques and Applications, RTA, 2004.

